

Team Structure

Name	Major/Year	Skills/Strengths	Experience/Interests	Subteam/Duty
Byunggon D Kim	Arch/5 th	Most of the Graphic and Vector Programs (AutoCAD, 3DSMAX, Rhino, Sketch-up, Photoshop, Illustrator, etc...)	Never had experience with robot other than playing with motored LEGOs, interested in Designing and learn about Robot	Mechanical
Erik Mead	EE/Senior	Knowledge of Microsoft Office Software. Also basic knowledge of circuit construction and troubleshooting.	Worked on another IPRO, interested in practical use of EE knowledge.	Mechanical, Chief Financial Officer
Neil Gupta	CS/Psych Freshman	Experienced in programming, especially Java and web design	Lots of coding experience, did some Robotics work in high school	Software
Mary DeRoo	EE/Junior	Knowledge of programming, robot design, and circuits.	Courses in programming, robot design, and circuits. Interested in applying classroom skills to real world situations.	Mechanical
Joy Bian	CPE/Junior	Knowledge of programming (C, Java, misc), robot design, circuits and hardware concepts	Courses in programming, robotics, electrical engineering. Interested in the applications of these fundamental concepts.	Software/Chief Information Officer
Karthik Dhagam	EE/Junior	Basic programming skills in C and Java. Hardware skills like circuits, machines/motors, Logic Gates, misc.	Worked as a technical intern with an embedded systems related company for three months. Interested to expand my knowledge programming.	Software

Alex Gordy	CS/Grad	“Expert” at Java. Intermediate C++ skills. Hardware/Software/Multicore knowledge	Constructed a robotic arm. Worked with AI and expert systems. Slight experience with neural networks. Interested in building concepts	Software
Siddhartha Raghuvanshi	MMAE/Junior	Basic Auto Cad skills, a little bit if idea about circuits as well as programming	No prior experiences but really interested in hardware parts and robotics designing and automotives.	Mechanical
Sarah Bowes	MMAE / Senior	Auto Cad, knowledge of robotics	Been on a robotics team and interested in the mechanical end of robotics.	Mechanical