iPRO 334 Robotics for Elderly Living Environments

Midterm Presentation 03.02.09



Problem Statement

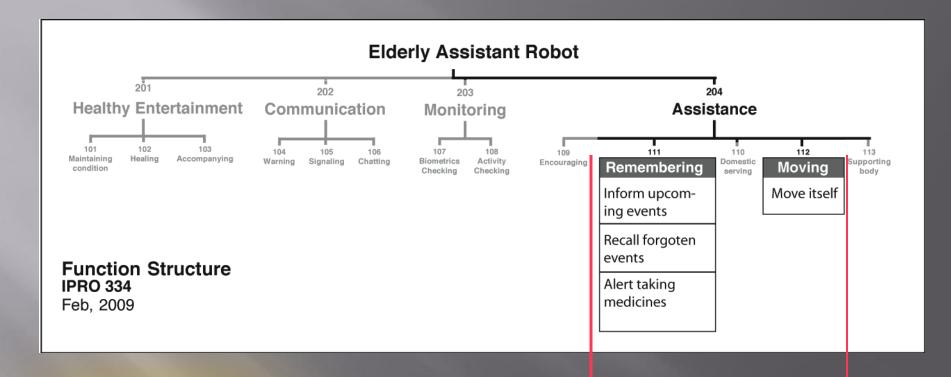
Less than 100 years ago, life expectancy was between 30 to 40 years. Today, close to 800 million citizens are 60 and over*.

As we age, our physical and health condition decline demanding assistance. The high costs of home health services and the shortage of caregivers are part of the future scenario for elder's population.

The intention of this project is to **create a robot to assist elderly & disabled patients in a long-term care facility or at home**. The ultimate goal of the team will be to develop a full-scale working prototype of the robot that will be able to move and interact with the surrounding area.

^{*} www.sharpbrains.com/blog/2008/11/13/the-future-of-the-aging-society-burden-or-human-capital/

Project Goals

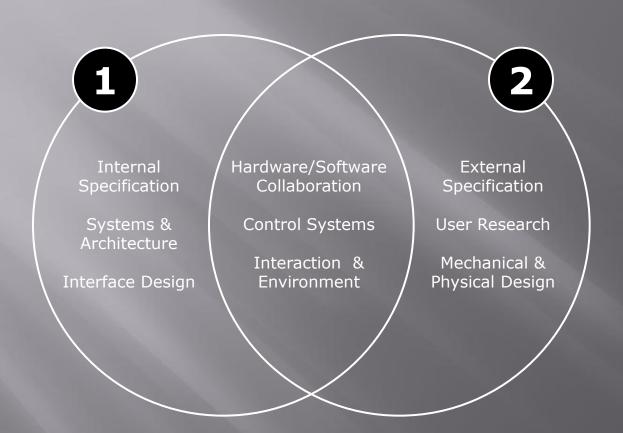




- Full-scale modulararchitectural structure
- Environmental simulation and user testing

- Working graphical interface
 - Full-scale working mobility

Team Organization



1. Electrical & Software

Computer science, electrical engineering, mechanical engineering.

Harmony Clauer Brent Frey Kevin Mooney Harshil Parikh Prashanthan Surendran

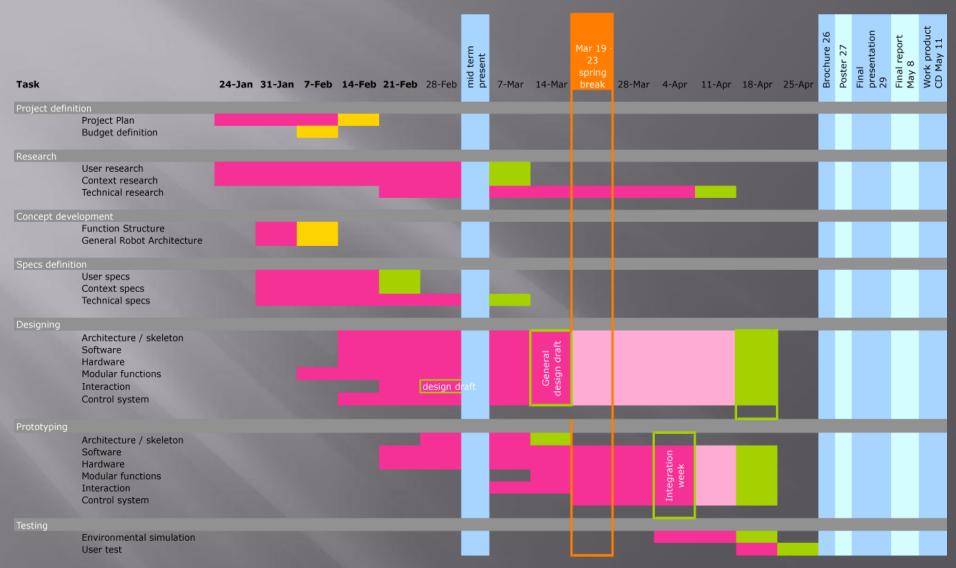
2. System Integration

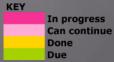
Institute of Design, psychology, mechanical engineering

Sarah Bowes
Jefferey Cink
Faye Garfinkle
Payaal Patel
Juan Salamanca
Grant Shindo

ROBOTIC SYSTEM APPLICATIONS TO HEALTCARE AND ELDERLY LIVING ENVIRONMENTS

Progress Towards Goals





Major Obstacles & Resolution



Defining Scope

Concept sketch session

Dimension specification diagram

Groupthink



Anticipated Challenges

Prototype

Translating concepts to articulated prototypes

Budget Constraints

Demonstrating working modules

Team

Integrating ideas from both teams

Relaying information between teams to meet a shared goal

