

I PRO Goals

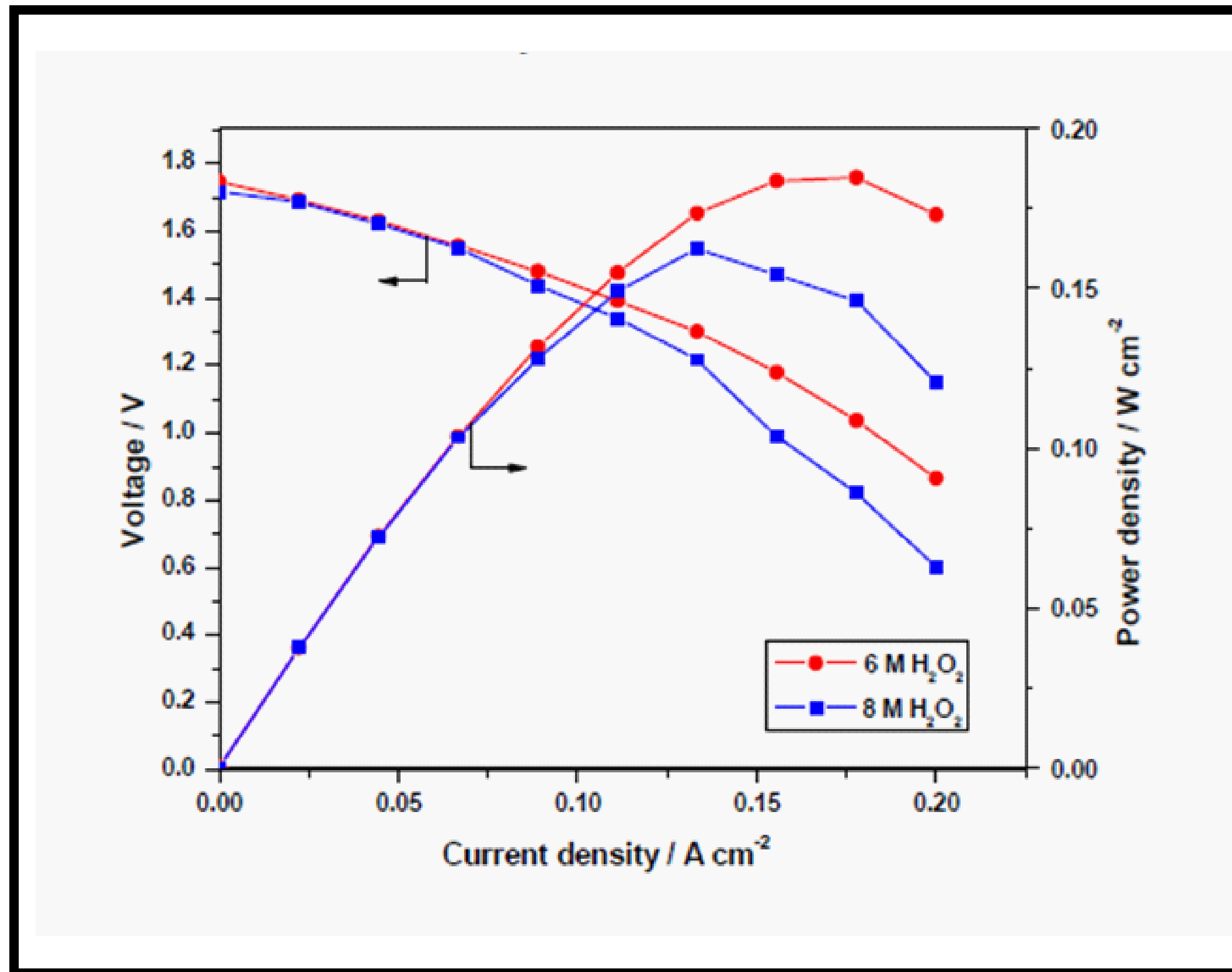
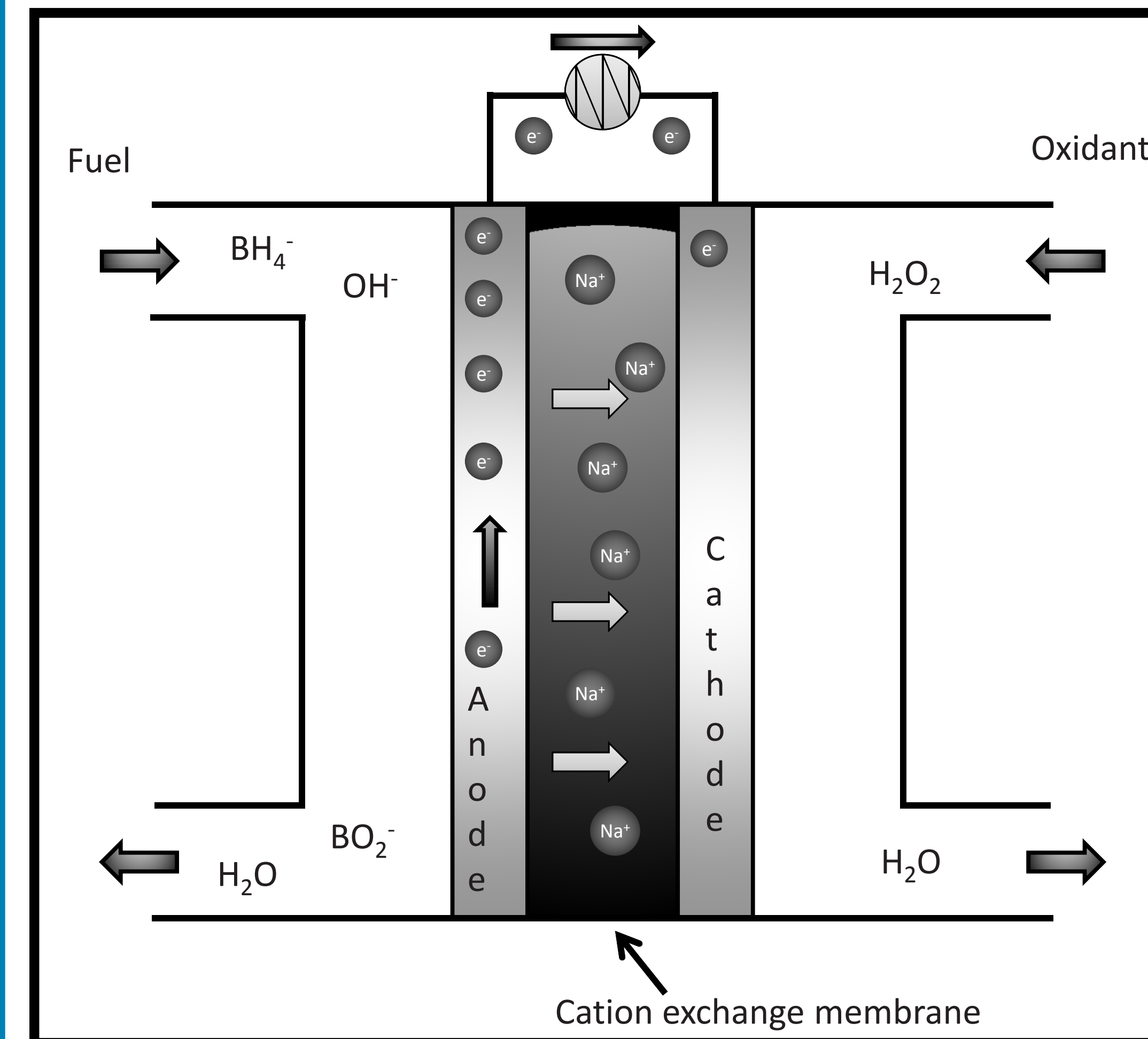
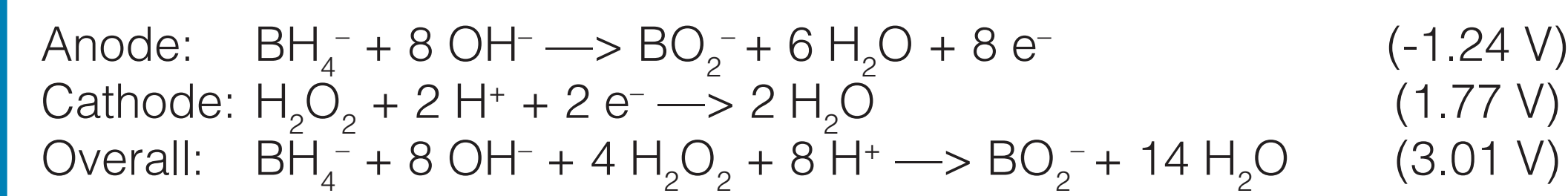
- Investigate potential use of fuel cell to power unmanned underwater vehicle (UUV)
 - Replace the use of conventional battery power
 - Research and design fuel cell power system
 - Design centered on a sodium borohydride (NaBH₄) fuel cell
 - Hydrogen peroxide oxidant (H₂O₂)
- Design a complete submersible package including:
 - Dimensions
 - Control surfaces
 - Material requirements

Fuel Cell Background

- Unmanned Underwater Vehicles (UUV) operate in conditions impossible for manned submarines
 - Naval applications for UUV's include reconnaissance and sabotage
 - Current UUV technology needs to improve on stealth and range
- Current fuel cell technology
 - Hydrogen polymer electrolyte membrane fuel cells most common
 - Research for UUV applications focus on NaBH₄ fuel cell
 - Two to three times more efficient than internal combustion engines
- NaBH₄ fuel cell technology
 - Relatively low environmental impact
 - Liquid reactions produce no gases in cell

Fuel Cell

The fuel and oxidant selected for this system was a sodium borohydride fuel and hydrogen peroxide oxidant. All relevant reactions are as follows:

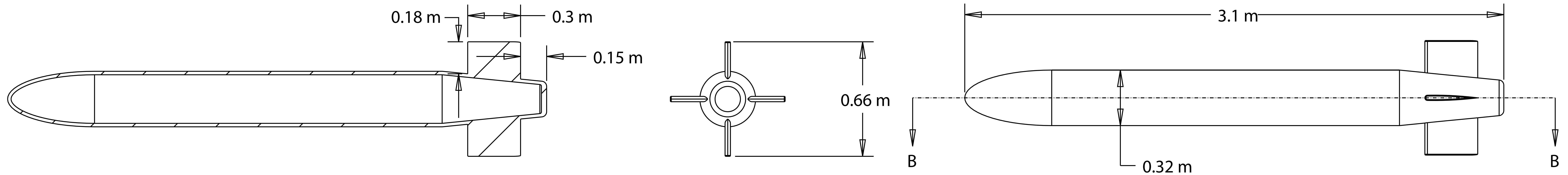
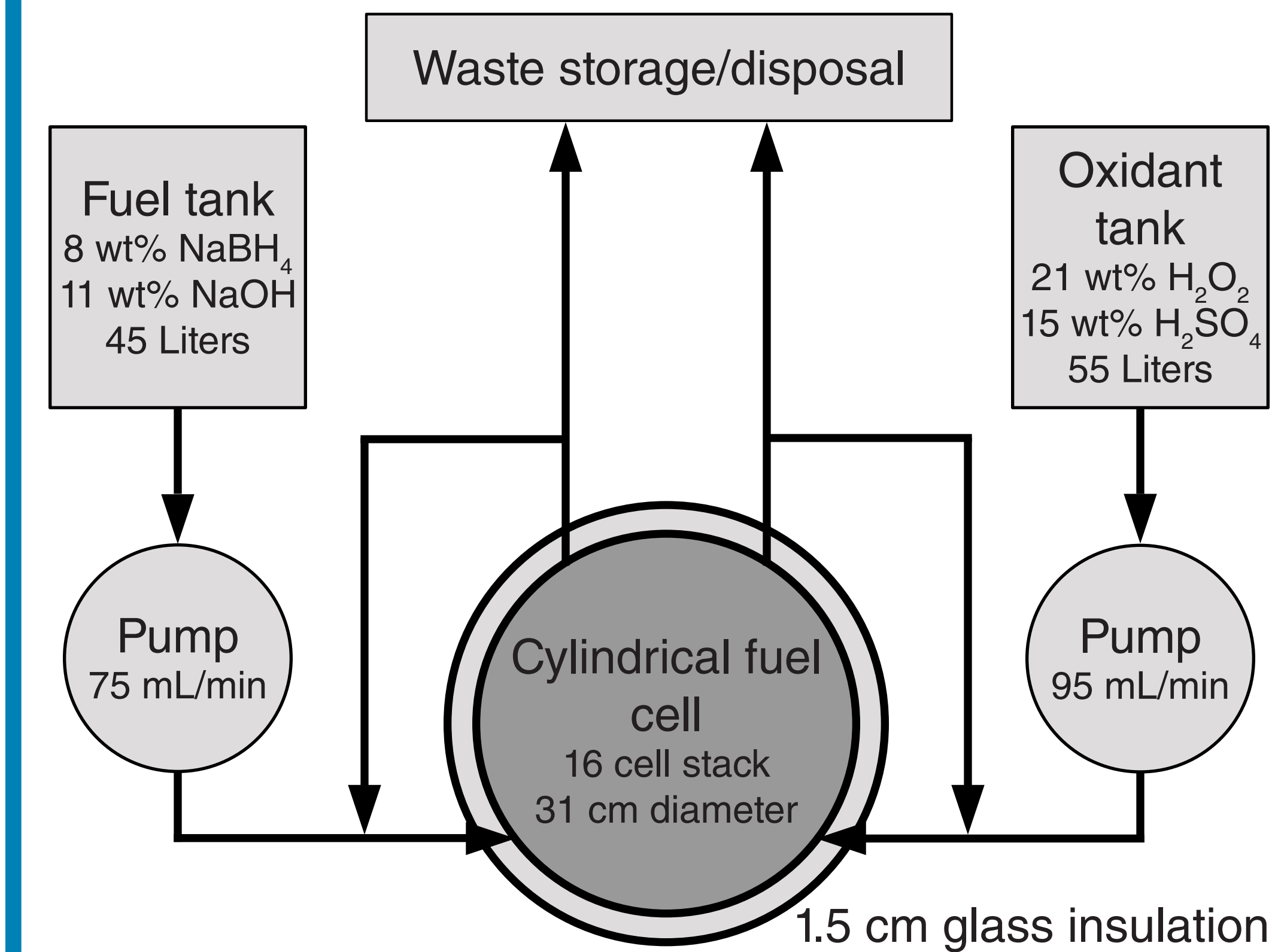


- Exact system specified using:
- Chemical reaction produces no gases
 - Minimal environmental impact
 - Power requirements estimated by propulsion group (2 kW)
 - Polarization data from literature¹ (above)
 - Specific membrane selection from literature (not shown) based on:
 - Sodium fouling resistance

Literature design overview

Fuel Cell Design Results

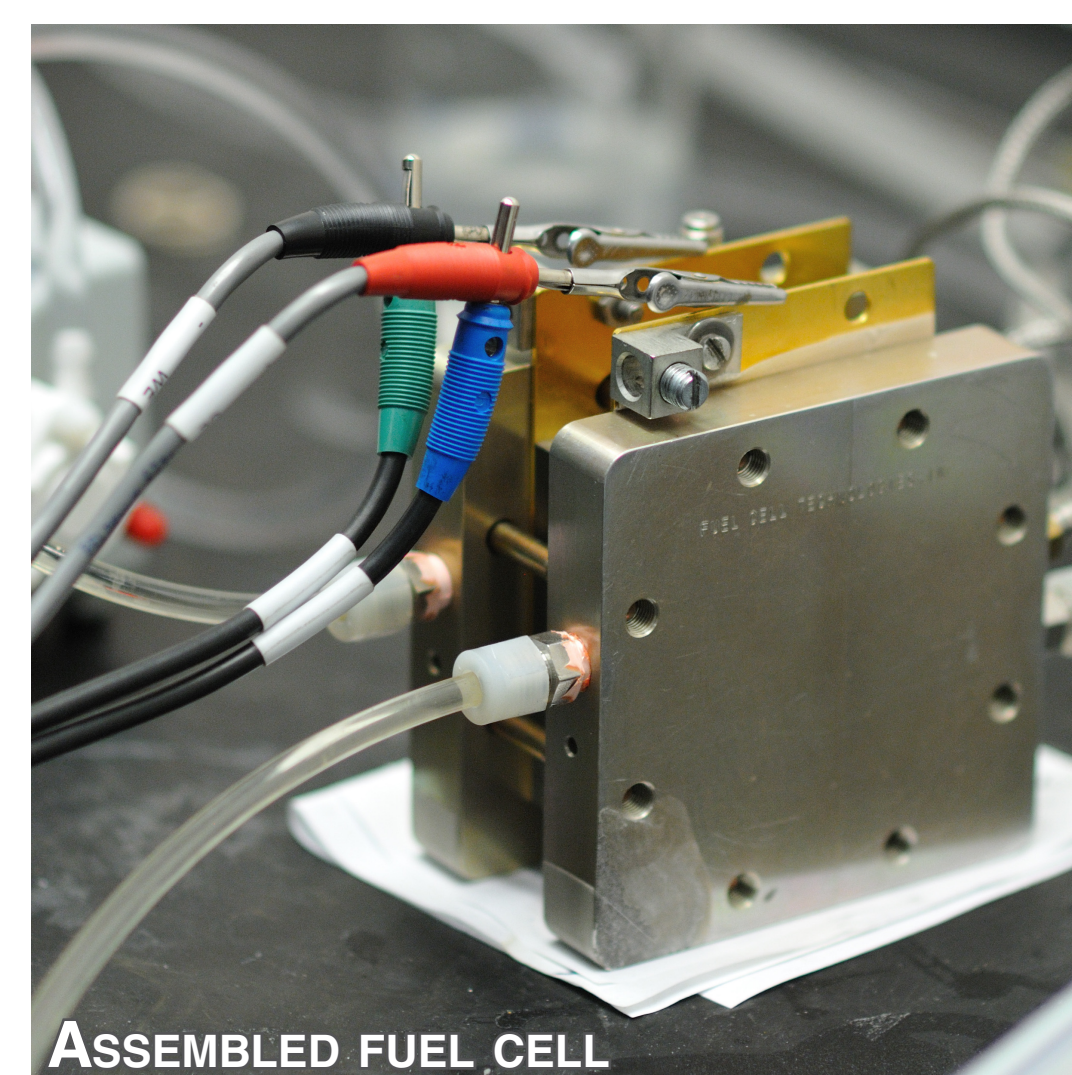
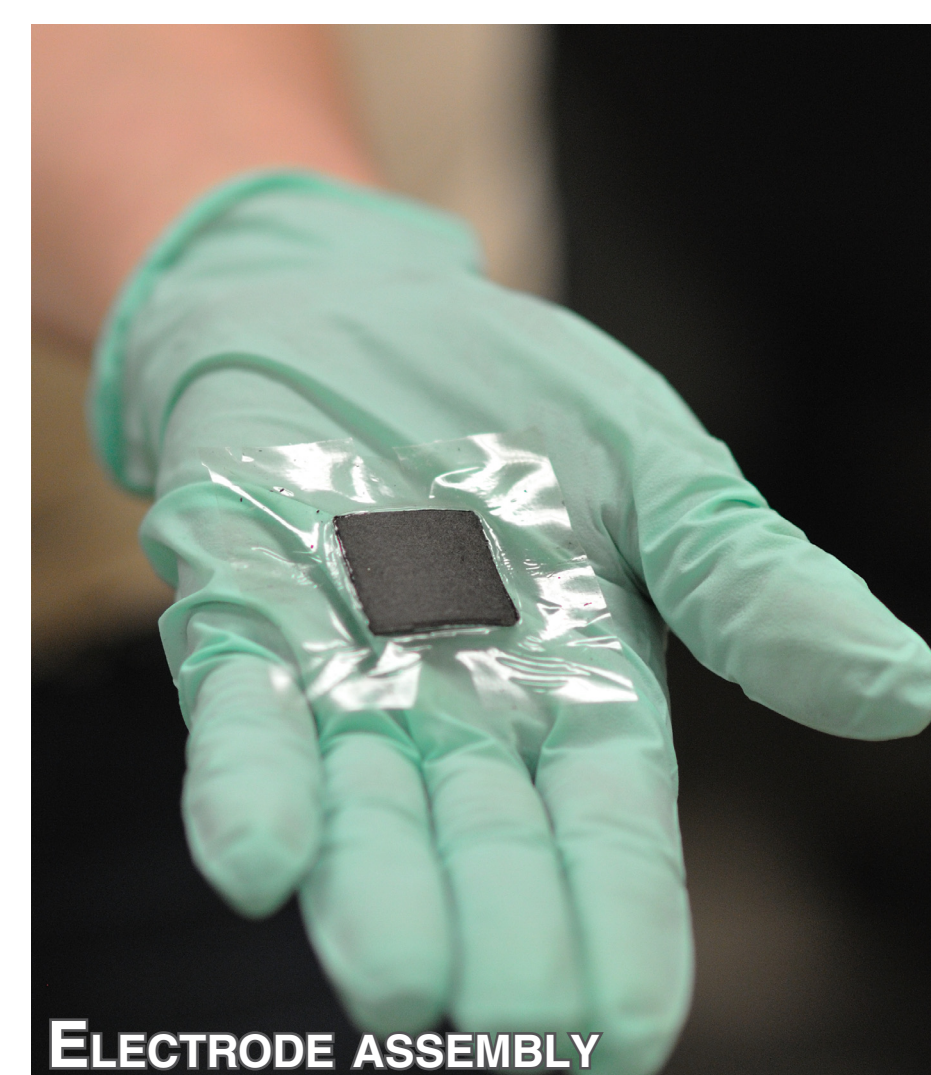
Number of cells	16
Cell operating voltage	1.5 V
Fuel cell length	29 cm
Fuel cell volume	23 L
Cell power output	2 kW
Cell voltage	24 V
Range	70 km



Experiments

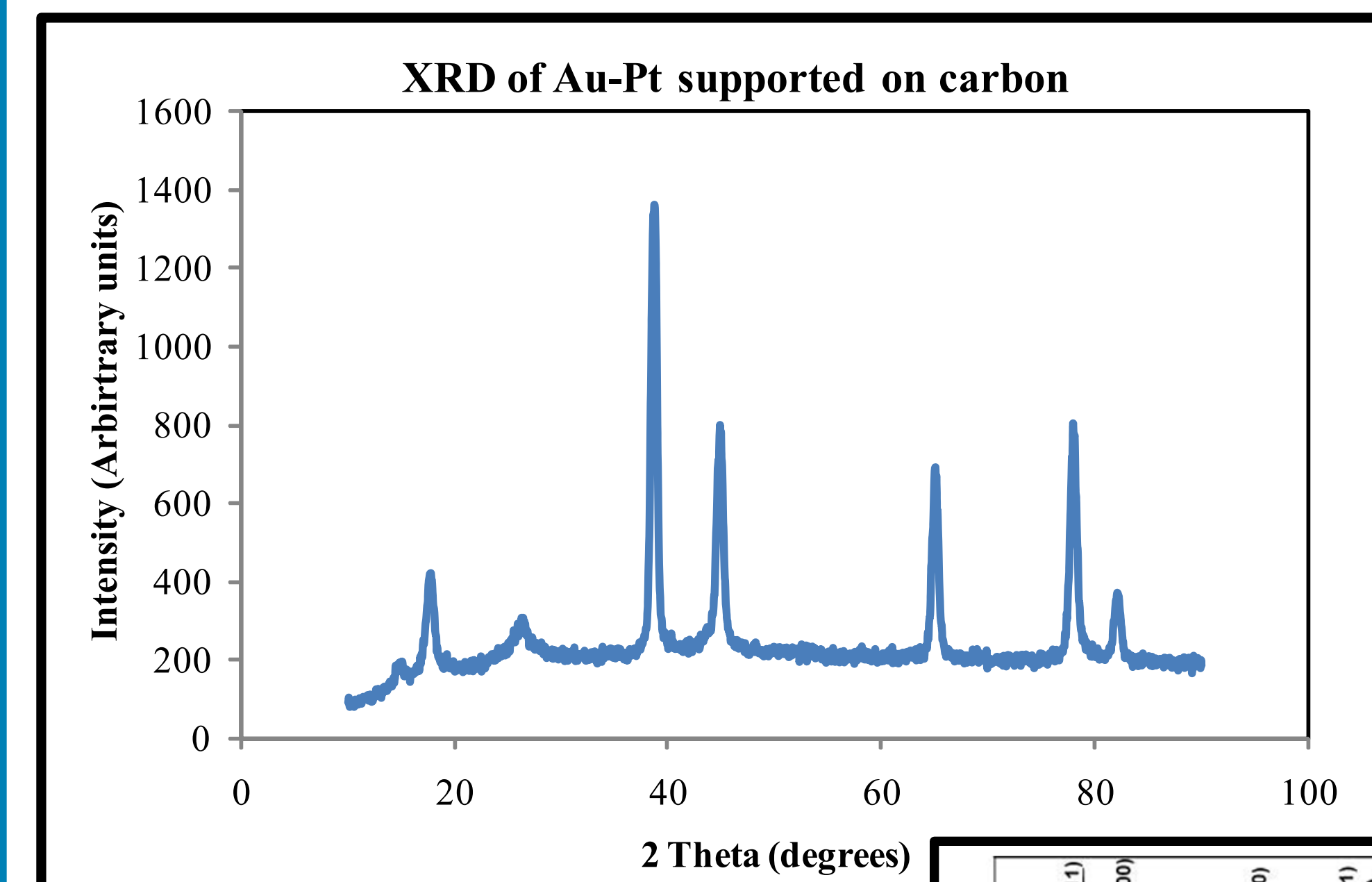
This project also included the creation and evaluation of an actual sodium borohydride fuel cell.

- Creation of a 97% gold/3% platinum on carbon catalyst.
- Assembly of the fuel cell.
- Evaluation of the fuel cell.
 - Polarization data (varying catalyst loading, membrane thickness and fuel concentrations)

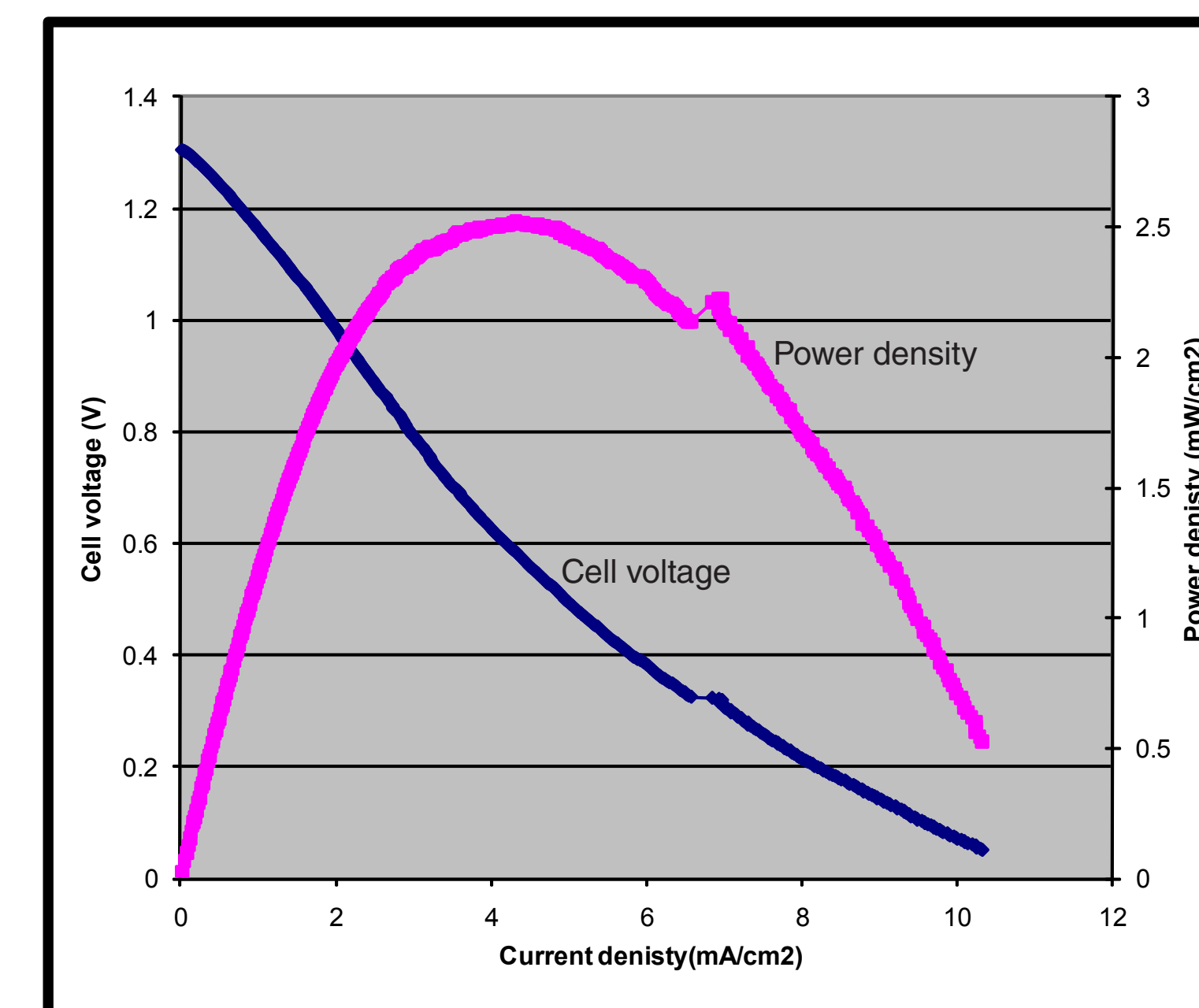
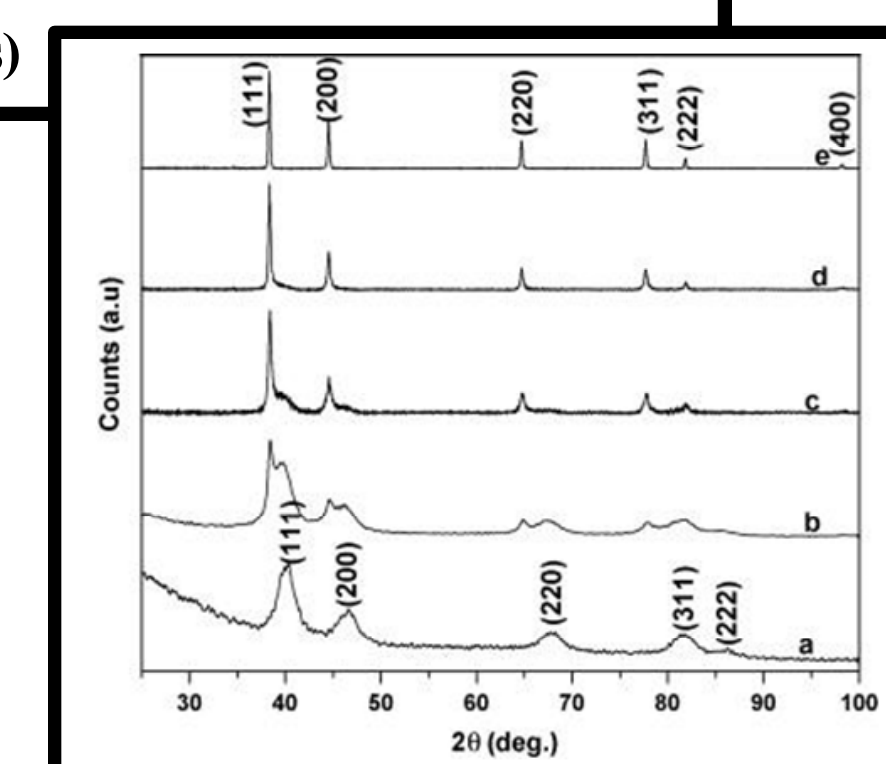


Experimental Results

- Two attempts to make catalyst, 97wt% Au, 3wt% Pt on carbon catalyst successfully made, XRD shown, reference shown below.



- Reference XRD³
- 100% Pt on carbon catalyst
 - 25% Au/75% Pt on carbon catalyst
 - 50% Au/50% Pt on carbon catalyst
 - 75% Au/25% Pt on carbon catalyst
 - 100% Au on carbon catalyst



- Fuel cell performance results presented above.*
 - Performance of second fuel cell using Nafion 117
 - Other trials used varied flow rates as well as Nafion 112
- Nafion 112 cell did not perform as well
 - Thinner Nafion not suitable for liquids

* More detailed results will be presented at I PRO Day, Apr. 23 at IIT's main campus

Environmental Concerns

- Concentrations of BO₂⁻ and BH₄⁻ are low enough to not impact environment in the event of a spill
- Other components in reaction degrade quickly in the environment
- H₂ produced in side reactions is in low enough quantities to not adversely effect ocean at depths

Future Work

There still remains a lot of work that needs to be completed before the entire UUV can be prototyped:

- Several more iterations of the power and space requirements within the UUV
- Effective methods of defouling the membrane from sodium ions

Bibliography

- A Self-Supported Direct Borohydride-Hydrogen Peroxide Fuel Cell System, Shulka A.K. et al, **Energies**, 2009, 2, 190-201.
- A Direct Borohydride/ Hydrogen Peroxide Fuel Cell with Reduced Alkali Crossover, Raman R. K., Shulka A. K., **Fuel Cells**, 2007, 3, 225-231.
- Journal of Power Sources: Volume 187, Issue 1**, Feb. 2009 page 19

Propulsion Background

- Survey of current technology
- Design a vessel around the propulsion system
 - > Theoretical design
 - > Practical design
- Fully specify and model a practical UUV
 - > Modeled in Pro/E

Initial Modeling

- Initial specifications were based off of research

	Small UUV	Medium UUV	Large UUV
Length (m)	1.5-3	5-7.5	10-15
Diameter (m)	0.20-0.40	0.60-1.0	1-2
Energy (kWh)	2.5	5.0	10.
Endurance (at 2 knots 1.03 m/s)	8 hours	4-6 hours	4 hours
Dry weight (kg)	100	200-300	300+

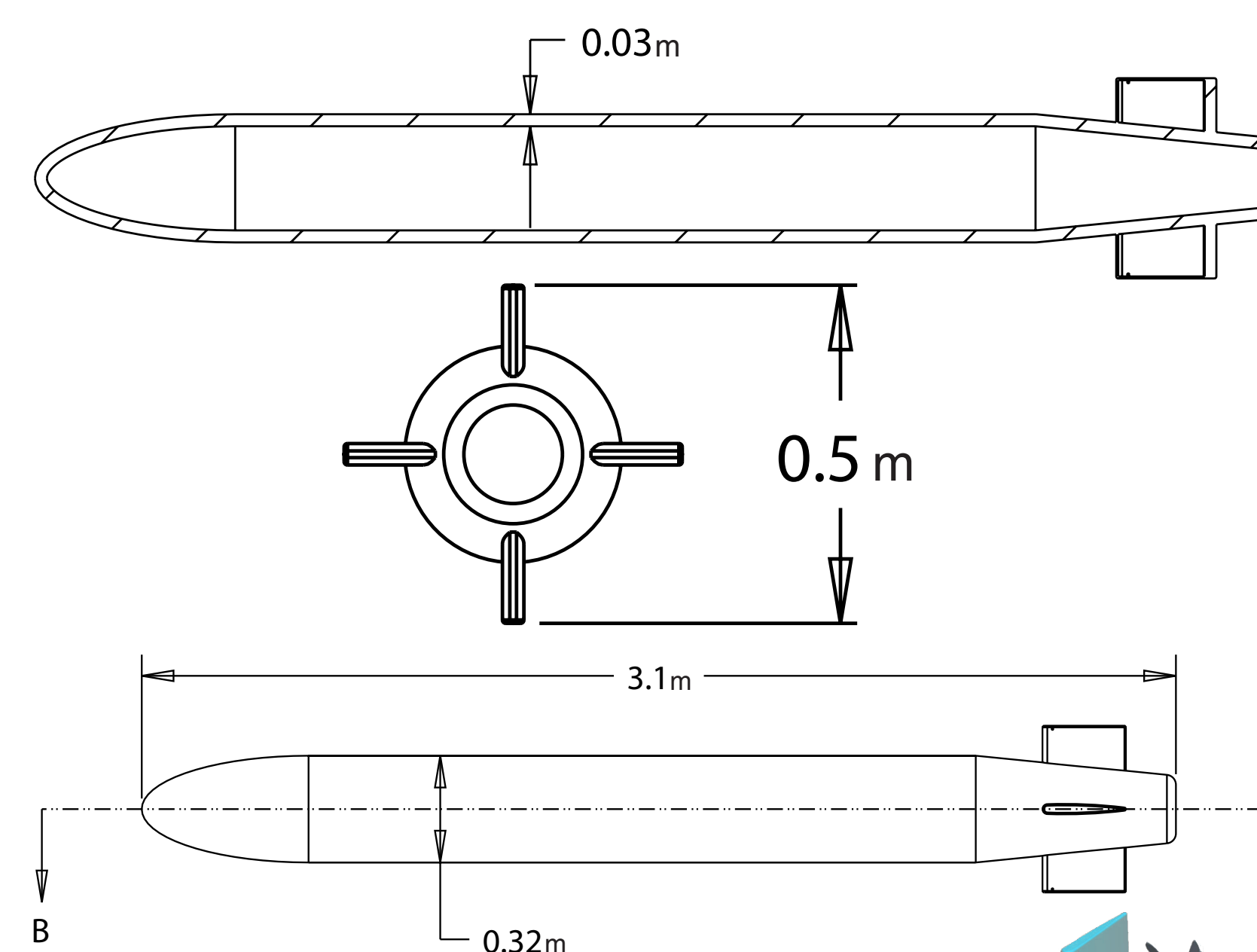
- Chose "medium" size
- Based initial dimensions off of a shortened Mk. 48 mod. 7 torpedo (current US torpedo)
 - > 5.79 m long
 - > 0.533 m diameter
 - > 1676 kg (with 295 kg warhead)
 - > Classified range ("greater than 5 miles")
 - > Classified depth ("greater than 1200 feet")
- Chose shorter length of ~3 m
- Chose narrower diameter of ~0.3 m
 - > Implied lighter weight of ~500 lbs (~225 kg)

Theoretical Design

Design criteria:

- "Medium" size (from table on the left)
- Quiet and ultra quiet operation
- Average sea water properties

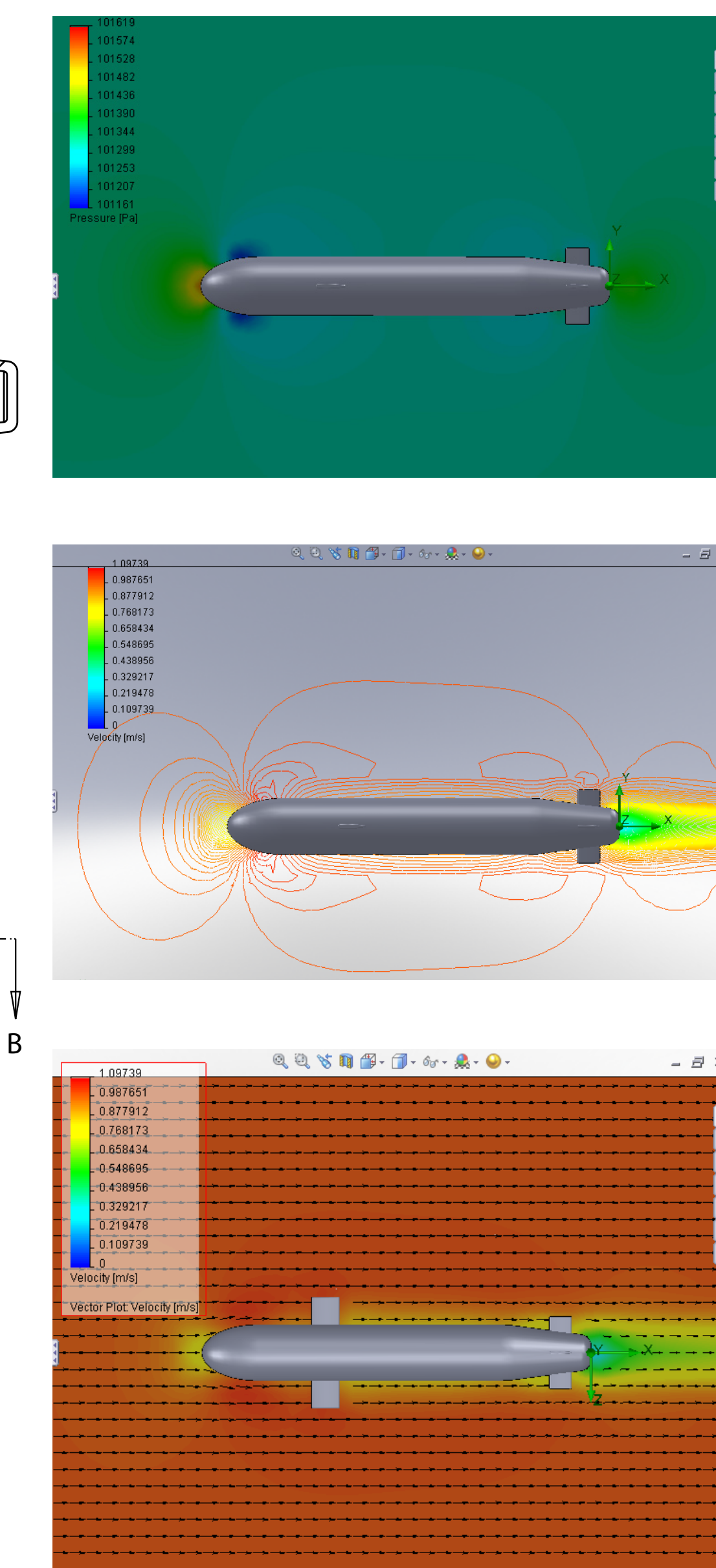
Initial sketches:



Initial estimates:

- 2 kW motor
- Steel hull
- 2 m/s max speed

Initial computations:



- Pressure calculations on initial design (Side/Top)

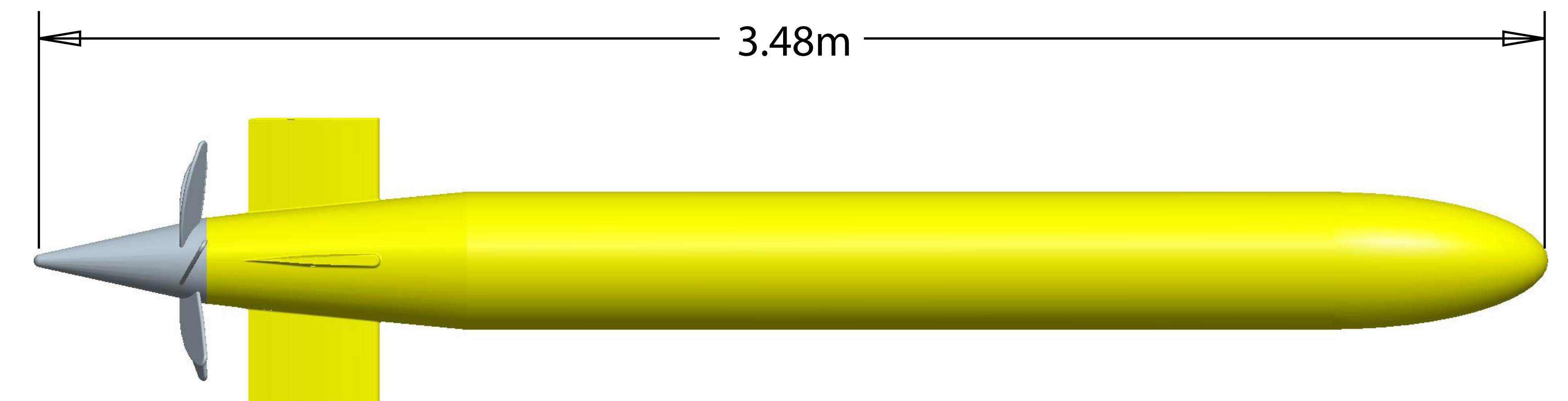
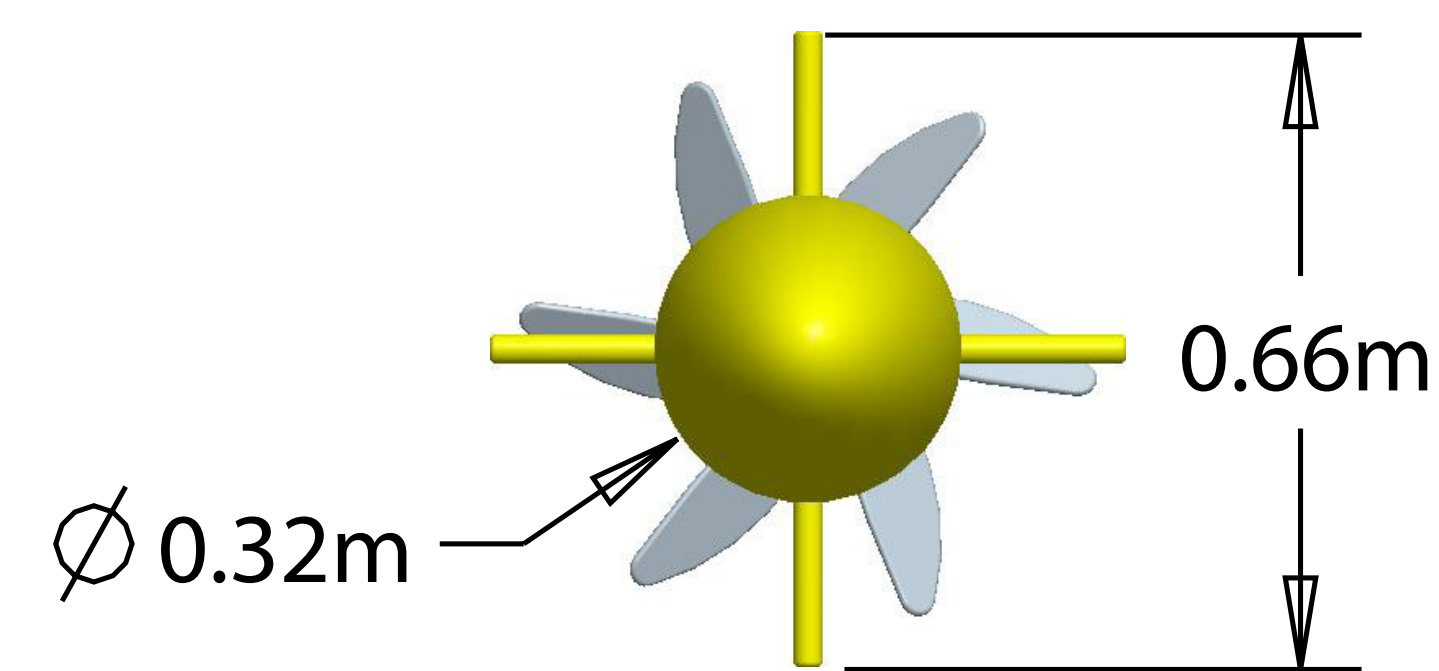
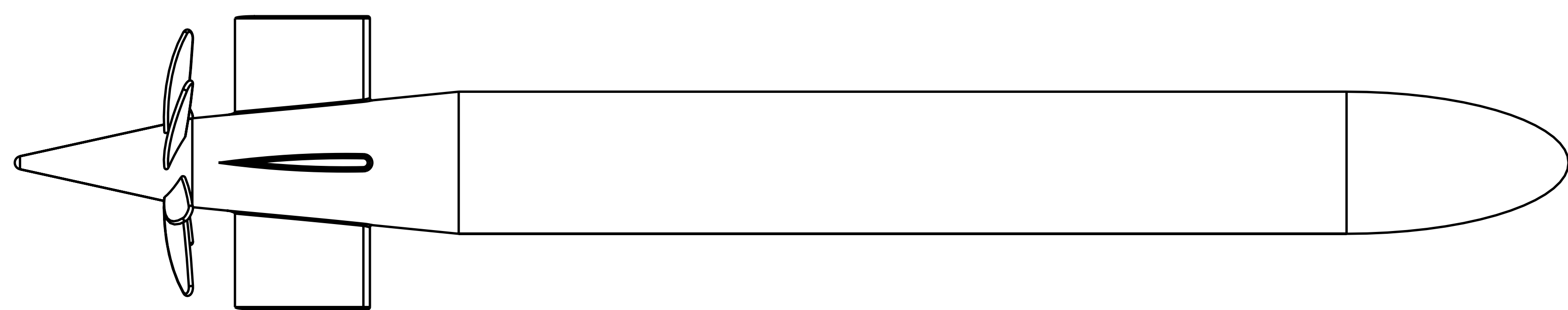
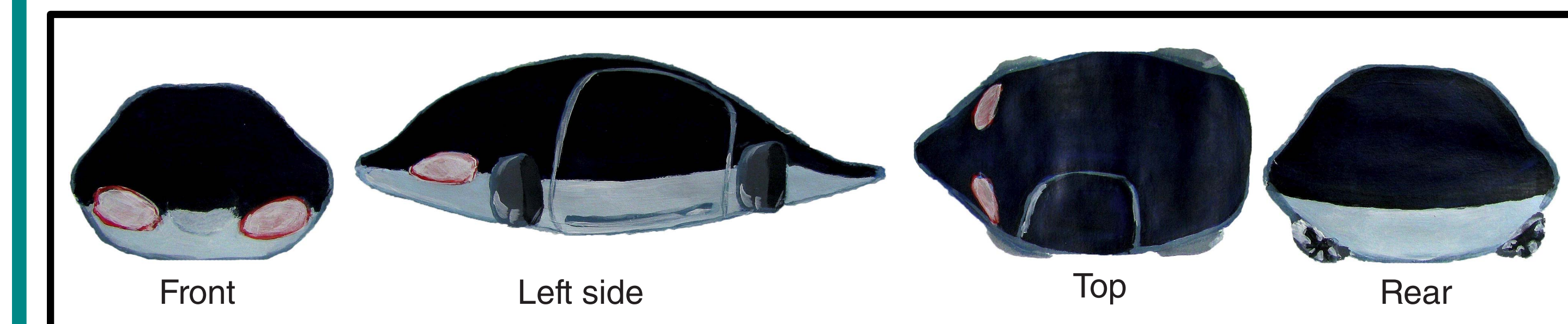
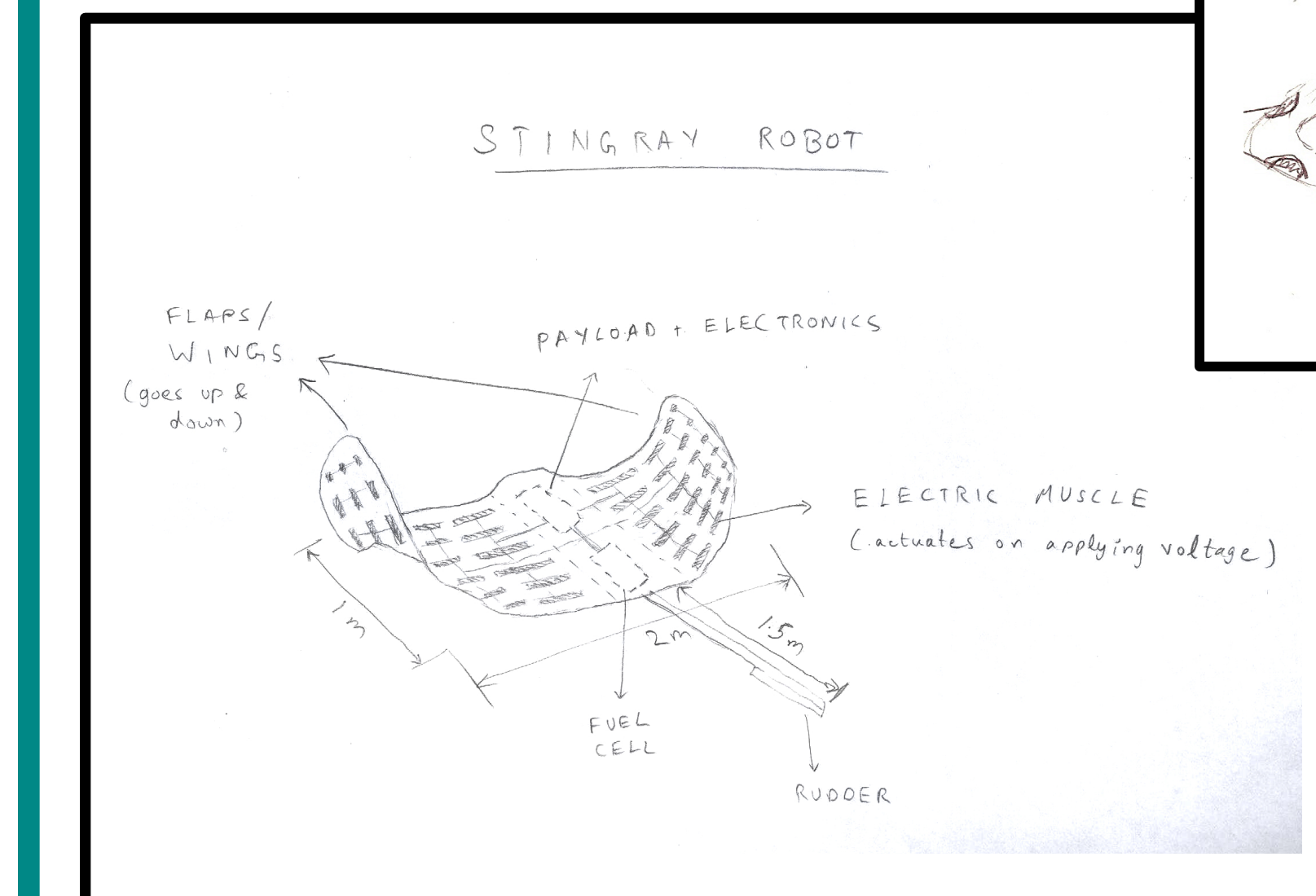
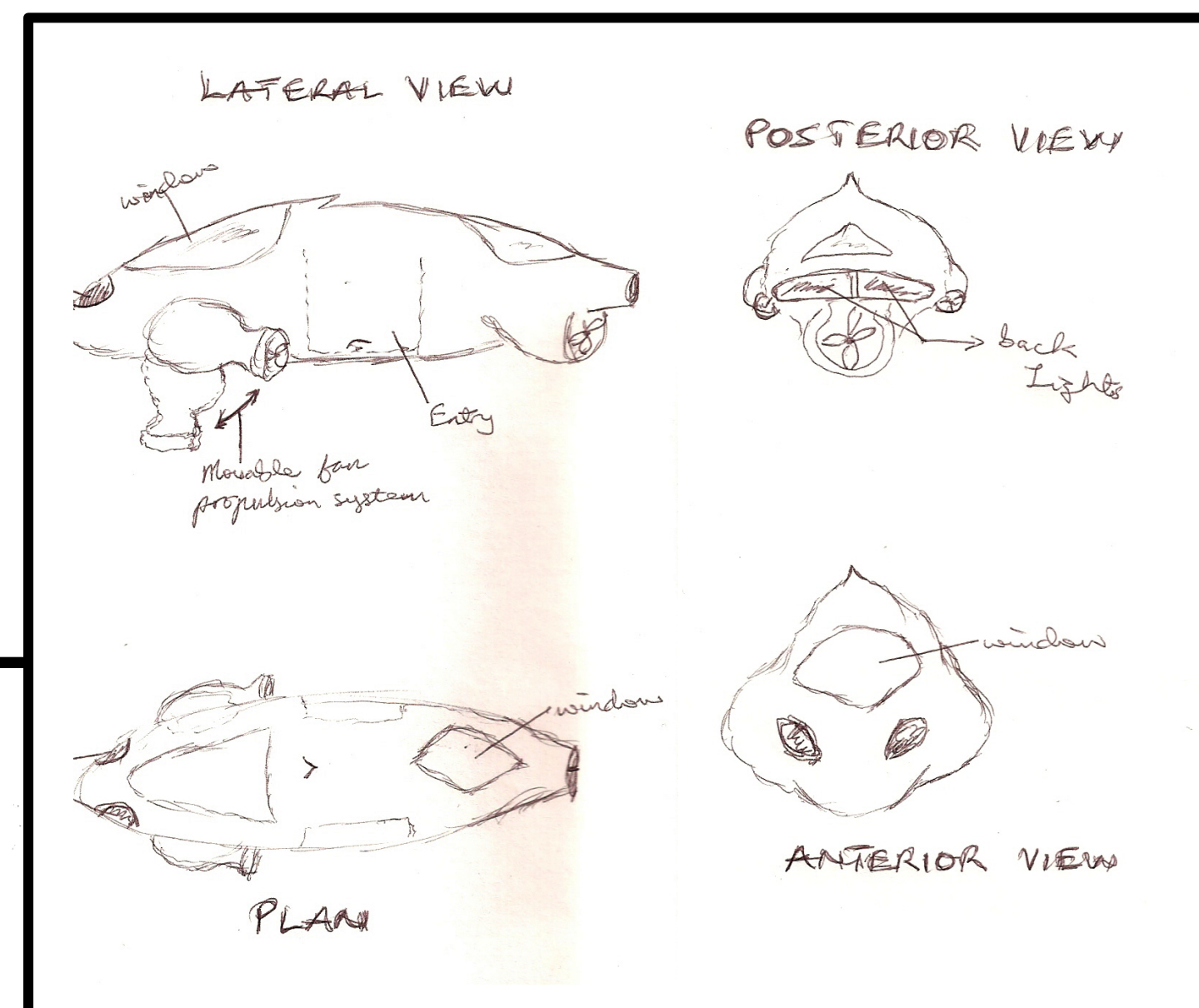
- Velocity contours (Side/Top)

- Velocity vectors (Side/Top)

Alternate Designs

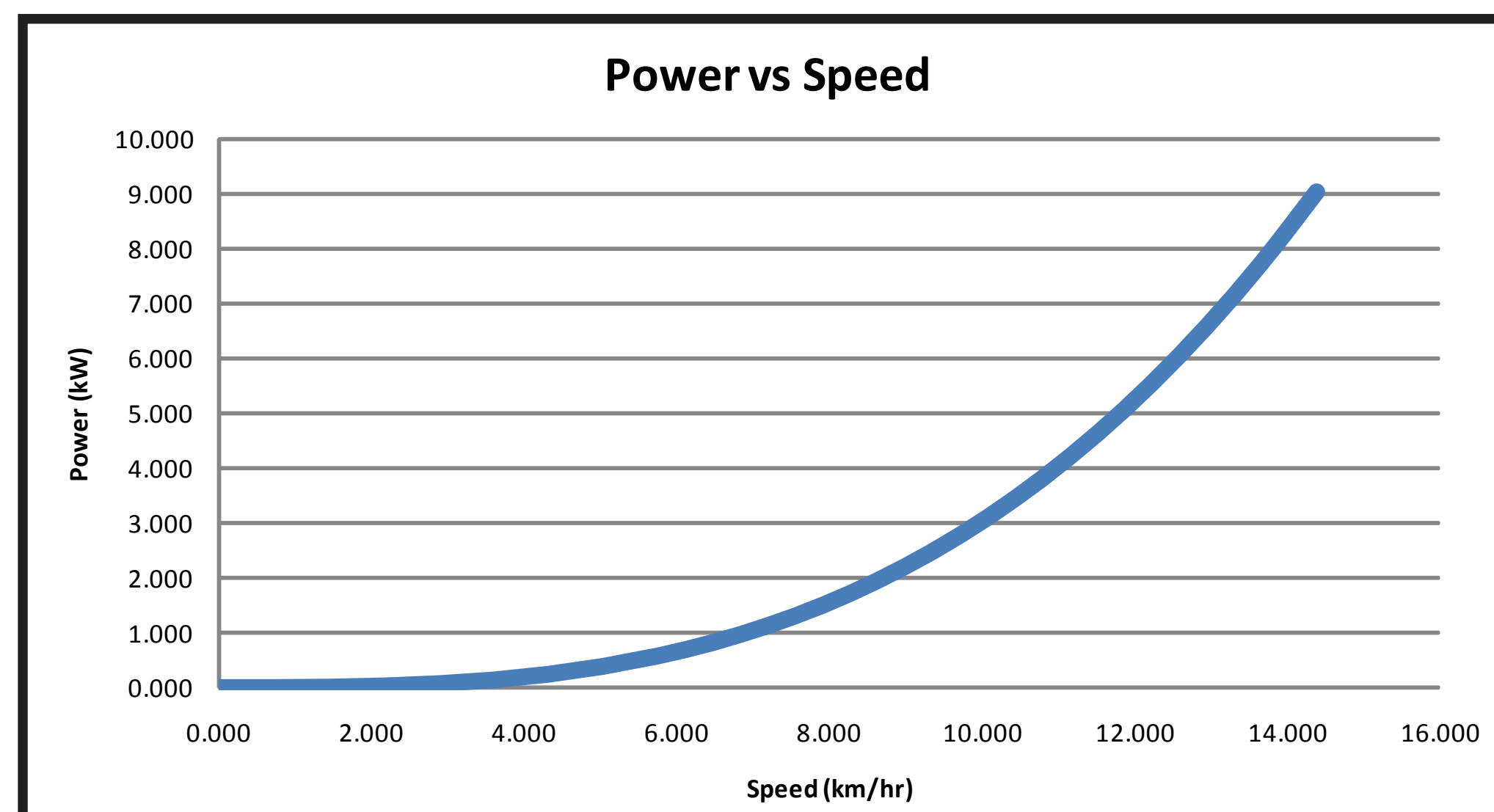
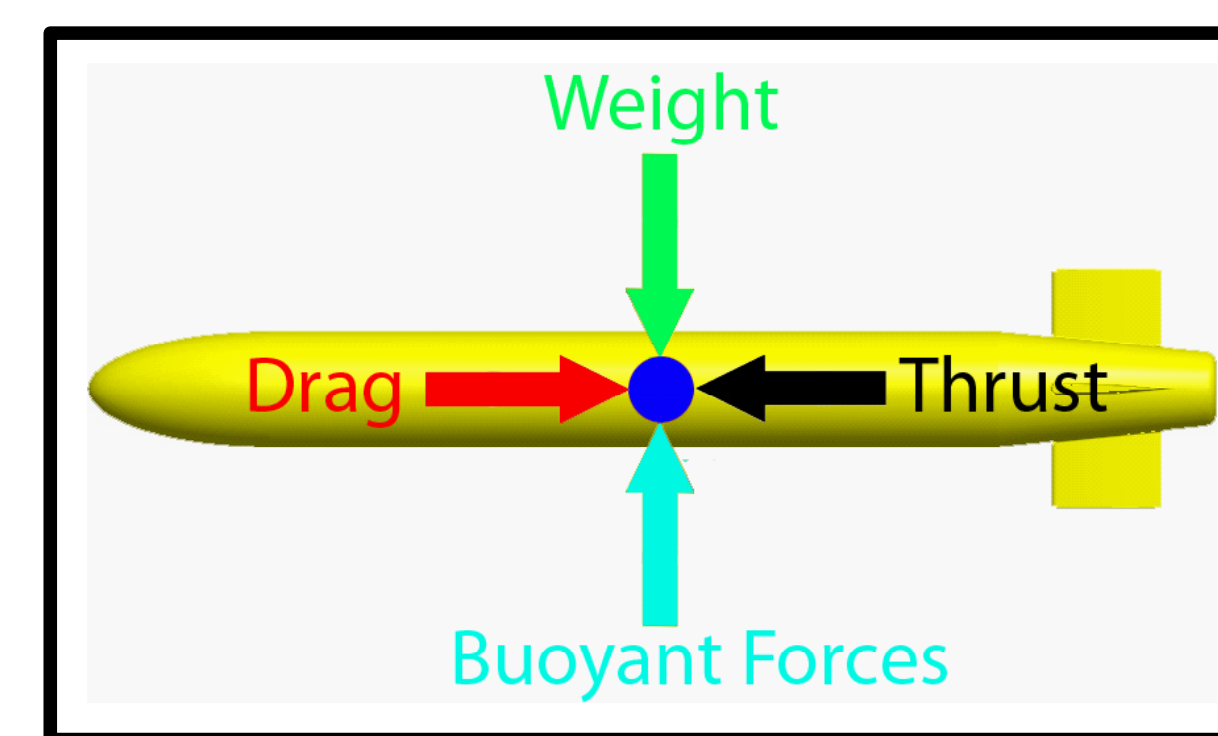
The propulsion team also explored more non-traditional designs, based more off of things that occur in nature.

- Designs not developed any further
 - > Modeling situation difficult as none of these systems have been tested before.



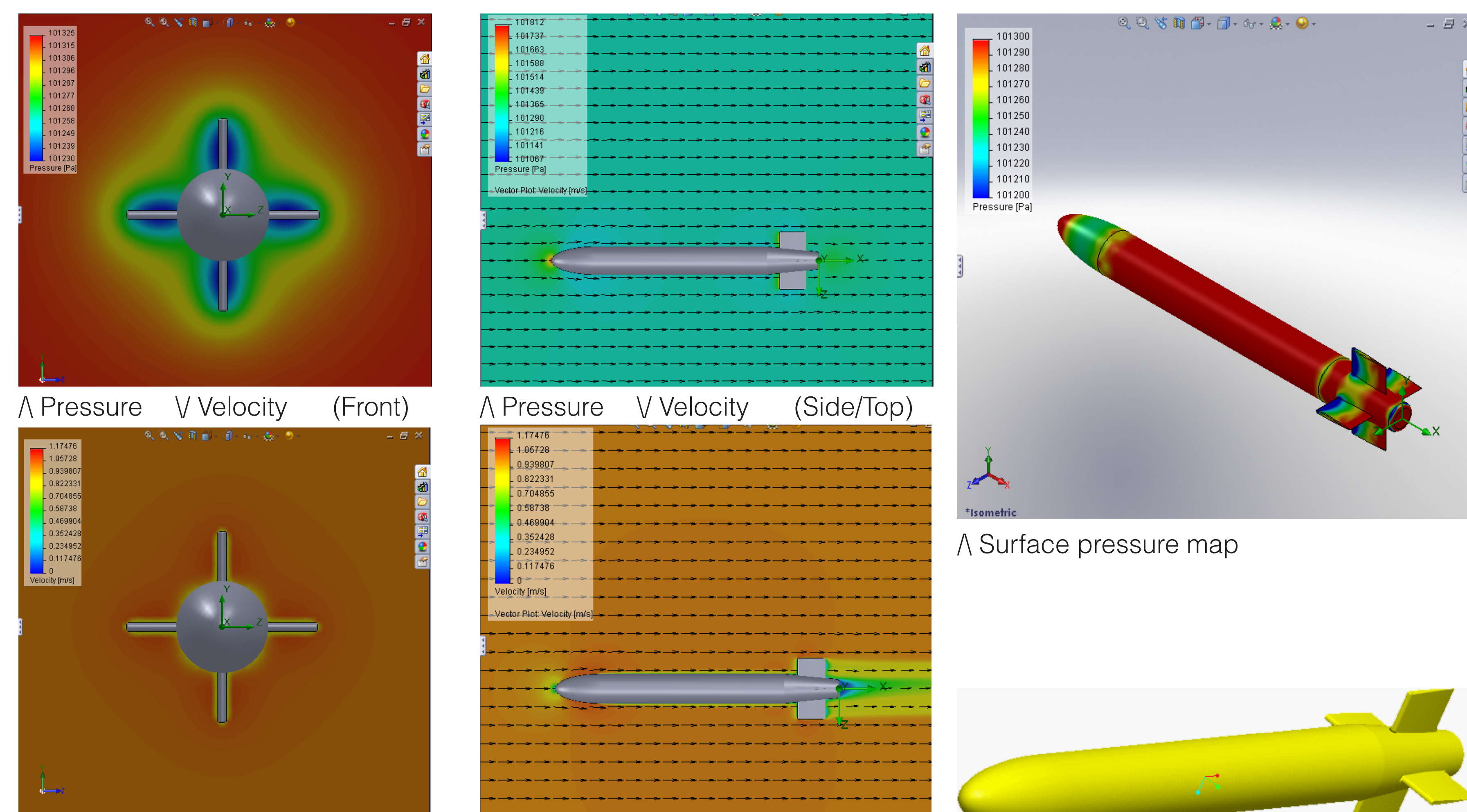
Sizing

- Initial engine size requirements were needed
- Final power determined to be approximately quadratic function
 - > Based off of research numbers, ~2 m/s chosen to be approximate speed
 - > 2 kW power supply determined



Simulations

- Design was further refined after initial calculations and sizing, with final models (with proper control surfaces) shown:



Future Work

- More refining on the hull shape to address stagnation issues
- More detailed drag calculations and material choices
- Detailed propeller design

Ethical Issues

- Minimal environmental impact with concentrations being used and intended environment
- Properly designing a control system to minimize impact to marine life
 - > Systems to avoid collisions with marine life
 - > Use of sensors that will not harm marine life
 - > Proper sealings to not impact operating environment
- No violations of current copy rights

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