IPRO 326 – Fall 2004 – Illinois Institute of Technology HYBRID ELECTRIC VEHICLES: Simulation, Design, & Implementation

INTRODUCTION

Increasing use of electrical power to drive automobile subsystems, which historically have been driven by a combination of mechanical and hydraulic power transfer systems, is seen as a dominant trend in advanced automotive power systems. This trend manifests itself through the more electric cars (MEC) concept, which is seen as the direction of automotive technology. The most practical and promising solution feasible for the automotive industry to achieve very high fuel economy and very low emissions through the MEC concept is hybrid electric vehicle (HEV) technology. In this IPRO, based on the previous student team works and guidelines set by Dr. Emadi, a team of eleven systematically tested both parallel and series vehicle configurations of the Hummer and HMMWV (High-Mobility Multipurpose Wheeled Vehicle) to find the optimum hybridization factor specific to each configuration. The team also worked in coordination with a Ph.D. student to simulate a hybrid electric bus system that is scheduled to have practical implementations in India by the end of the year. In addition, the team reviewed the FutureTruck 2004 Competition, which involved designing a most energy-efficient truck with a hybrid-electric drive train; the team used data from this competition to work on a more efficient mechanical design of a hybrid drive train. All vehicle simulations and structured testing were performed using ADVISOR, as well as other software packages available in the Power Electronics and Motor Drives Laboratory at IIT.



IPRO 326 Team (Fall 2004)

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SIMULATION TOOL: ADVISOR

ADVISOR is an Advanced Vehicle Simulator that simulates the performance of hybrid electric, conventional, electric, and fuel cell vehicles. The software was created by the U.S. Department of Energy's (DOE) Office of Transportation Technologies' (OTT) Hybrid Vehicle Program. ADVISOR calculates the fuel economy, emissions released, acceleration times, and much more for a given drive cycle.

Simulation Parameters:



Vehicle Input Custon Jonfiguration using Custon Eloch Jingram Component Plot Selection fuel_converter v fc_efficiency Fuel Converter Operation Geo 1.0L (41kW) SI Engine - transient data Acc Electrical ? acc elec options Powertrain Control par ? man Y PTC_PAR View Block Diagram)_PAR_SimplorerDer P.15 P.15 0 1000 2000 3000 4000 Component fuel_converter Component Component fuel_converter Component Compo

Vehicle Input Parameters:

Result:



CONVENTIONAL VEHICLES



Highway Fuel Economy Certification Test (HWFET)

HYBRID ELECTRIC VEHICLES

HEVs are promising the most practical more electric solution to reach very high fuel economy and very low emissions. Reasons:

- > Use of smaller internal combustion engines (ICE)
- > Operate the ICE at its maximum efficiency region
- > Effectiveness of regenerative braking to recharge the batteries







Drive Cycle Module

Engine speed (rpm)



Engine Efficiency Map



Energy consumed in braking which is lost in conventional vehicles, but recovered in HEVs.



Motor Efficiency Map

SERIES DRIVE TRAIN CONFIGURATION



PARALLEL DRIVE TRAIN CONFIGURATION



CO₂ NOx Fuel Consumption HC (MPG) **Parallel HEV** 61.0 0.32 0.98 0.28 **Conventional Car** 40.4 0.42 0.45 2.47 Improvement(%) 37.8 50.9 47.5 60.3



HYBRID DRIVE TRAIN MECHANICAL DESIGN

Series Configuration:





	Fuel Consumption (MPG)	НС	CO ₂	NOx
	80.0	0.41	1.26	0.34
r	40.4	0.61	2.47	0.45
)	98.0	32.8	49.0	24.4

	Fuel Consumption (MPG)	НС	CO2	NOx
	98.7	0.20	0.64	0.17
r	40.4	0.61	2.47	0.45
)	98.0	32.8	74.0	62.2

Parallel HEV Control Strategy

Hybridization Factor (HF)





Parallel Configuration:



OUR TECHNICAL APPROACH

The Hybridization Factor (HF) is the ratio of the electric motor in comparison to the total vehicle power. The optimum HF yields the highest fuel economy for the vehicle. In this IPRO, we utilized two different test methods for each of the series and parallel vehicle configurations to determine the optimum hybridization factor.

- For the H2 and HMMWV Parallel Configuration:
 - Method 1: Total Vehicle Power Constant
 - Method 2: Internal Combustion Engine Power Constant
- For the H2 and HMMWV Series Configuration:
 - Method 1: Total Motor Power Constant
 - Method 2: Internal Combustion Engine Power Constant

IPRO 326

Our technical team organization:



HMMWV: PARALLEL CONFIGURATION

Simulation Methods

1) Constant Total Power Engine is scaled from 100% to 30% and motor is scaled from 0% to 70% in increments of 5%

Fuel Economy Charts & Results



2) Varying Motor Power Motor is scaled from 0% to 70% in increments of 5%, and engine kept Constant at 100%



		Acceleration			Fuel Economy (mpg	
	Ŧ	0-30mph	0-50mph	Max Speed	Cty	Highway
Conventional		10.70s	334s	80.5mph	10.6	188
Hybrid Method 1	0.5	960s	1856	95.6mph	15.2	232
Hybrid Method 2	0.4	840s	17.0s	105.9mph	99	189

Conclusion:

Both the performance and fuel economy of Method 1 increased when compared with conventional values. However only the performance, not the fuel economy, of Method 2 hybridized Parallel HMMWV increased.

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HMMWV: SERIES CONFIGURATION

Simulation Methods

1) Constant Motor Power: Engine and generator are scaled from 100% to 30% in increments of 5% **Fuel Economy Charts & Results**

2) Varying Motor Power:: Motor power is changed between 60% and 140% in increments of 5%



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	0	20	40	60	80	100	120
	-		-		Motor Pr	wor (kW)	
					WOTOF PC	wei (kw)	

		Acceleration		Fuel Economy		omy (mpg)
	HF	0-30 mph	0-50 mph	Max Speed	City	Highway
Conventional		9.5s	27.8s	87.8mph	10.8	18.8
Hybrid Method 1	0.2	6.4s	17.9s	80.6mph	20.2	19.4
Hybrid Method 2	0.05	7.0s	18.7s	80.7mph	19	20.5
Max Improvement		26.30%	35.60%	-8%	87%	9%

Conclusion

Both the performance and fuel economy of the hybridized HMMWV M1097 A2 result in high increase when compared with conventional values.

Note: The battery power is the least that could meet the UDDS cycle expressed in number of battery modules.

H2: PARALLEL CONFIGURATION

Simulation Methods

1) Constant Total Power Engine is scaled from 100% to 30% and motor is scaled from 0% to 70% in increments of 5%

Fuel Economy Charts & Resultsc

2) Constant Total Power in increments of 5%

Fuel Economy Method 1 -----0.4 0.05 0.3 0.5 Hybridization Facto

		Acceleration			Fuel Economy (mpg	
	HF	0 - 60 mph	1/4 mile	Max Speed	City	Highway
Conventional		9.8 s	17.9 s	101.2 mph	9.6	13.8
Hybrid Method 1	0.05	10.3 s	18.2 s	101.7 mph	11.1	15.8
Hybrid Method 2	0.212	9.5 s	17.5 s	115.3 mph	10.9	16.4
Max Improvement		5%	2.20%	14%	15.60%	188%

Conclusion:

The change in performance of the hybridized H2, except max speed of method 2, is negligible, while both methods dramatically increase fuel economy





Engine is scaled from 100% to 30% and motor is scaled from 0% to 70%



H2: SERIES CONFIGURATION

Simulation Methods

1) Constant Motor Power: Engine and generator are scaled from 100% to 30% in increments of 5% **Fuel Economy Charts**





		Acceleration			Fuel Economy	
	HF	0 - 60 mph	1/4 mile	Max Speed	City	Highway
Conventional		9.8 s	17.9 s	101.2 mph	9.6	13.8
Hybrid Method 1	0.35	14.1s	19.6s	96.5	21.6	17.6
Hybrid Method 2	0.2	31.6s	23.8s	72.2	5.7	6.3
Max Improvement		-44%	-9.50%	-5%	40.60%	54.30%

Conclusion:

Fuel economy of the hybridized Hummer H2 increased for method 1 and decreased for method 2. Performance decreased for both methods when compared with conventional values.

HYBRID BUS SYSTEM RESEARCH

Method of Simulation

Varying Motor Power The motor power was ranged from 0% to 70% of 150 kW in increments of 5%

Fuel Economy Charts & Resultsc



		Fuel Economy (mpg)		
	HF	City	Highway	
Conventional		4.9	5.5	
Hybrid Method 1	0.35	5.9	7.2	
Max Improvement		20.40%	31%	

Conclusion:

The performance of the hybridized electric bus is amplified greatly after incorporating an electric motor.

Optimum Hybridization Factor = 35%

2) Varying Motor Power:: Motor power is changed between 60% and 140% in increments of 5%

