# Hybrid Lego Bus Model Demonstrates

The Lego bus model was built to demonstrate these hybrid concepts:

- **Regenerative Braking:** The idea of a hybrid is to charge the battery using the electrical motor as a generator when braking.
- Planetary Gears: Planetary gears are one of the innovative systems available to enable the electrical motor and the ICE to work individually or in tandem, for the most efficient way to power the vehicle.
- Visual Demonstration of Mechanical Concepts: Overall the Lego bus is a useful model which helps one to visualize the mechanical systems of a hybridized bus.





Picture courtesy of Wikipedia.org

# Picture courtesy of HowStuffWorks.com

## **Power Split**

## **Objective:**

• Select a power split or coupler that is able to efficiently combine power ratings for an electric machine (EM) and an internal combustion engine (ICE) in order to send the combined power to the drive shaft

## **Regenerative Braking:**

• Allows the ICE to generate energy to charge the battery packs when braking occurs

## Solution:

- Planetary gear box with the EM and ICE as inputs and the drive shaft as the output
- The EM acts as both the electric machine and also as a generator for regenerative braking



# Lybrig Lego Bus Mogel





**Drive Shaft** 

## **Objective:**

• Find a suitable drive shaft that will transfer power efficiently from the ICE and the EM to the loads at the wheels

## Solution:

- Use solid drive shafts along with universal joints and pillow block design
- 303 stainless steel type should be used to avoid corrosion



Picture courtesy of VictoriaBritish.com









• A simple open differential is a device which serves to supply power to the two wheels attached to it while allowing them to rotate at different speeds.

Various types of Differentials and their Feasibilities: • There are several types of differentials available. These differentials are the Limited Slip Differential Locking Differential and (LSD), the another differential based on the components found in the ABS (Anti locking Braking System).

# Solution:

• On the test bed the wheels will not experience any traction, this eliminates the need for the alternatives to the open differentials.



the mechanical supporting structure for the

components under all modes of operation while preserving acceptable component alignment

"I" sections that is similar to standard bus frame

## **Differentials Differential Gear Background Information:**



## **HEV Test Bed**

Hybrid cars are a newer option on the market, designed to increase the efficiency of vehicles. While there are already hybrid cars on the market with a standard design, there are limited ways to demonstrate the effectiveness of hybrids. A prime candidate for hybridization is a school bus, which frequently stops, carries children, and runs routes daily. Thus, this two semester IPRO has designed and will build a test bed that demonstrates why school busses should hybridize.

### Introduction

An electrical motor running on a lithium ion battery was fitted on an ordinary (RC) car model. This model was used for testing hybridized acceleration. The RC car would first run on just the ICE and then with the electrical motor attached. The modifications involved the mounting of the electrical motor and the battery pack on the chassis of the traditional RC Car model.







# IPRO 342: Hybrid Electric School Bus Test Bed



**Contact:** http://www.iit.edu/~ipro342f06/

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# Performance

- motors.

# Efficiency

- Electric motors are more efficient over a wide range of speeds, but are often less powerful than ICEs.
- ICEs are more powerful, but are only moderately efficient, and only over a small range of speeds.
- Using both in combination, efficiency can be maximized while still meeting the power and speed demand.



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• Electric motors respond well to rapid changes in power, but tend to be less powerful than ICEs.

• Using both in combination, the availability of instantaneous power is improved, as is the total power available, improving performance.

• ICEs tend to have substantial "lag" associated with changes in power, but tend to be more powerful than

- weaknesses.
- other.





# How this Car was Hybridized (for Performance)

- gearing.





# **Reasons to Hybridize**

• The two most common mechanical drives, electric motors and internal combustion engines (ICEs), each have strengths and

• Depending on the circumstances, one is more desirable than the

• Initially, the car possessed only an ICE for power. This was supplemented by the addition of a DC motor.

• The DC motor is attached in parallel to the ICE at the drive

• Throttle control for the ICE and current control for the motor are run from the same RC channel. When the vehicle is made to accelerate, both the ICE and motor supply power.

## Dyno

- The Dyno tests the motor using three phase power for hybrids showing the effectiveness of the small system modeling.
- The electrical circuitry can be used on the larger scale test bed.
- The inverter converts DC voltage to AC voltage.
- This provides an opportunity to explore the function of dSpace.



# **Current Sensors**

The current sensor is able to tell which of the phases, A, B, or C, are on or off to tell dSpace which position the motor is in.

# **Isolator Circuit**

It keeps high power circuitry electrical isolated from the dSpace system in case of circuit failure.

## dSpace

- The dSpace system contains real-time hardware based on PowerPC technology and I/O interfaces: ideal for developing an electric motor controller.
- The installation of a dSpace system, upgrades any PC to a powerful development environment for rapid prototyping.
- dSpace provides a real-time interface for motors to Simulink/MATLAB to graphically display the motor functions, the I/O, and to control the motor.
- Reduces time spent debugging code.

### **Lead Acid Battery Pack** 🗠 | 🕨 = |Inf 🛛 Normal 💽 | 🔛 🛗 😰 🍪 🔛 | 🚂 🔯 📷 🛞 High power to weight ratio. SLAVE BIT IN DS1104SL\_DSP\_BIT\_IN\_C0 SLAVE BIT IN DS1104SL\_DSP\_BIT\_IN\_C1 SLAVE BIT IN DS1104SL\_DSP\_BIT\_IN\_C2 • Less expensive compared to NiMH batteries. Readily Available - SLAVE BIT OUT DS1104SL\_DSP\_BIT\_OUT Terminator1 Enc position Enc delta position DS1104ENC\_POS\_C1 Gain Charge Time: 5-10 Hours ENCODER SET POSITION ENCODER MASTER SETUP Life Span: 3-4 years or about 200 Charges start 🛛 🥭 👆 🚳 🕎 Document 1 - Microsof... p ControlDesk Develop... 📣 MATLAB Command Wi... 🙀 hall 🧷 🖗 😰 🗘 4:2



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Feedback

Conditioning

Circuitry

dSpace

-Motor Position Feedback-

Power

Electronic

Converter

Power

Source

- An inverter is used to convert DC to AC.
- MOSFETs are a key part in the inverter circuit, they are used as ON/OFF switches.
- A Gate Driver is also needed in the inverter to amplify 5 volts to 15 volts.

- The base of the dyno provides a stable, rigid support for the motors and other moving parts.
- To keep mechanical losses low, vibration must be kept to a minimum.
- High rigidity keeps vibration amplitude low.
- Component alignment is held to tighter tolerances, keeping components from vibrating
- Wood base improves rigidity of bed, and also absorbs some vibration
- Reinforcing bars improve rigidity of brackets



# **Power Electronics**

• The battery supplies one phase power, the inverter converts it to three phase power required by the motor.







# **Mechanics**

stator.

## Solution:

- has several advantages:
- ✓ Very high torque to inertia ratio
- ✓ Very high peak torque

- ✓ No sparking due to brush wear
- isolator, and current sensors.





# **Electric Motor**

• The turning of the rotor is caused by magnetic fields which are created by running current through the windings in the

• Of the possible motor types the permanent magnet (BLDC)

✓ Zero out-gassing (no brush dust)

✓Very high reliability (no commutator or brush to wear out) ✓ Potentially higher efficiency (due to no brush friction)

• The decision to use a brushless motor requires the design of an electronic solid state switch system including an inverter,

Picture courtesy of Wikipedia.com