

PEPPY ROBOT

*OBJECTIVE

- Design and manufacture the self-powered mobile and autonomous robots
- Creating a powerful personal robot

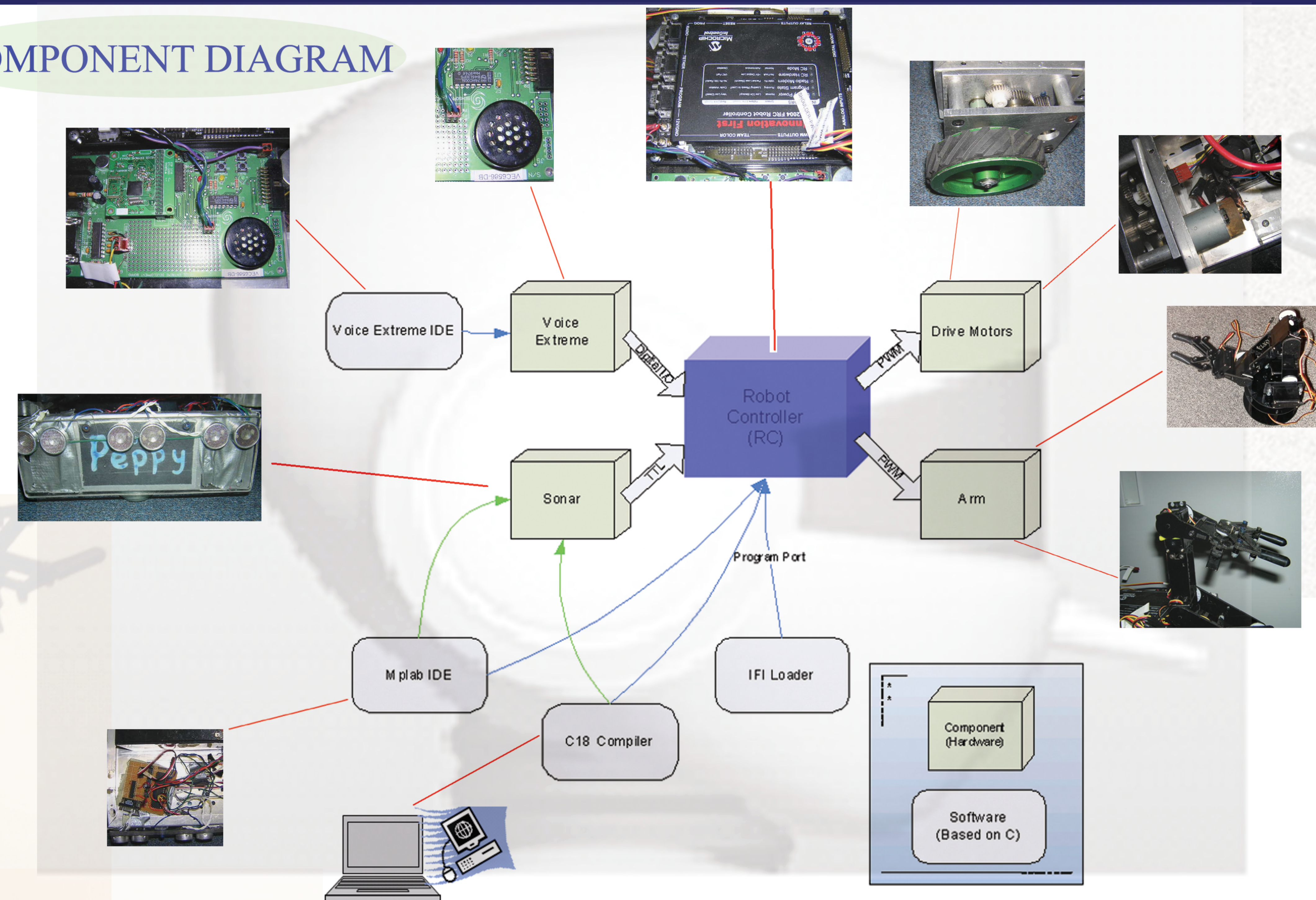
*PROJECT TIME LINE

ID	Task	Start	End	Req. time	2005	2006	2007
1	Approach	2005-08-07	2005-08-18	2w			
2	Reverse modules	2005-08-28	2005-09-11	2w			
3	Repair Peppy	2005-09-21	2005-09-28	7w			
4	Update software	2005-09-02	2005-09-19	7w			
5	Chassis design	2005-09-09	2005-09-19	6w			
6	Documentation	2005-09-25	2005-09-28	9w			
7	Design presentation	2005-09-25	2005-09-28	2w			

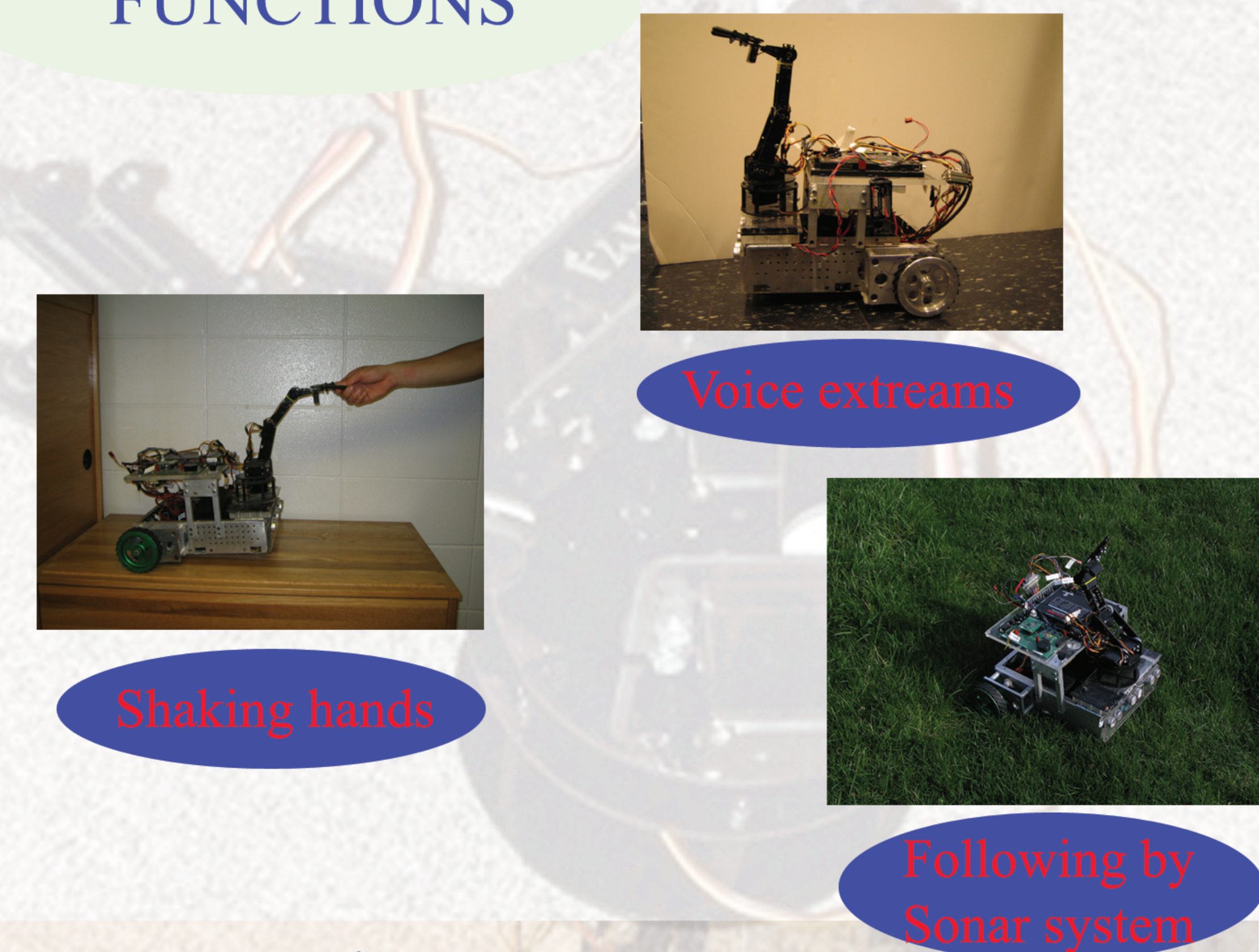
*TEAM MEMBERS

Bong Gun Sin (LEADER)
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*COMPONENT DIAGRAM



FUNCTIONS



*CONCLUSION

- Successful repairing process for Peppy
- Functionally well modified Peppy
- Successful chassis redesign

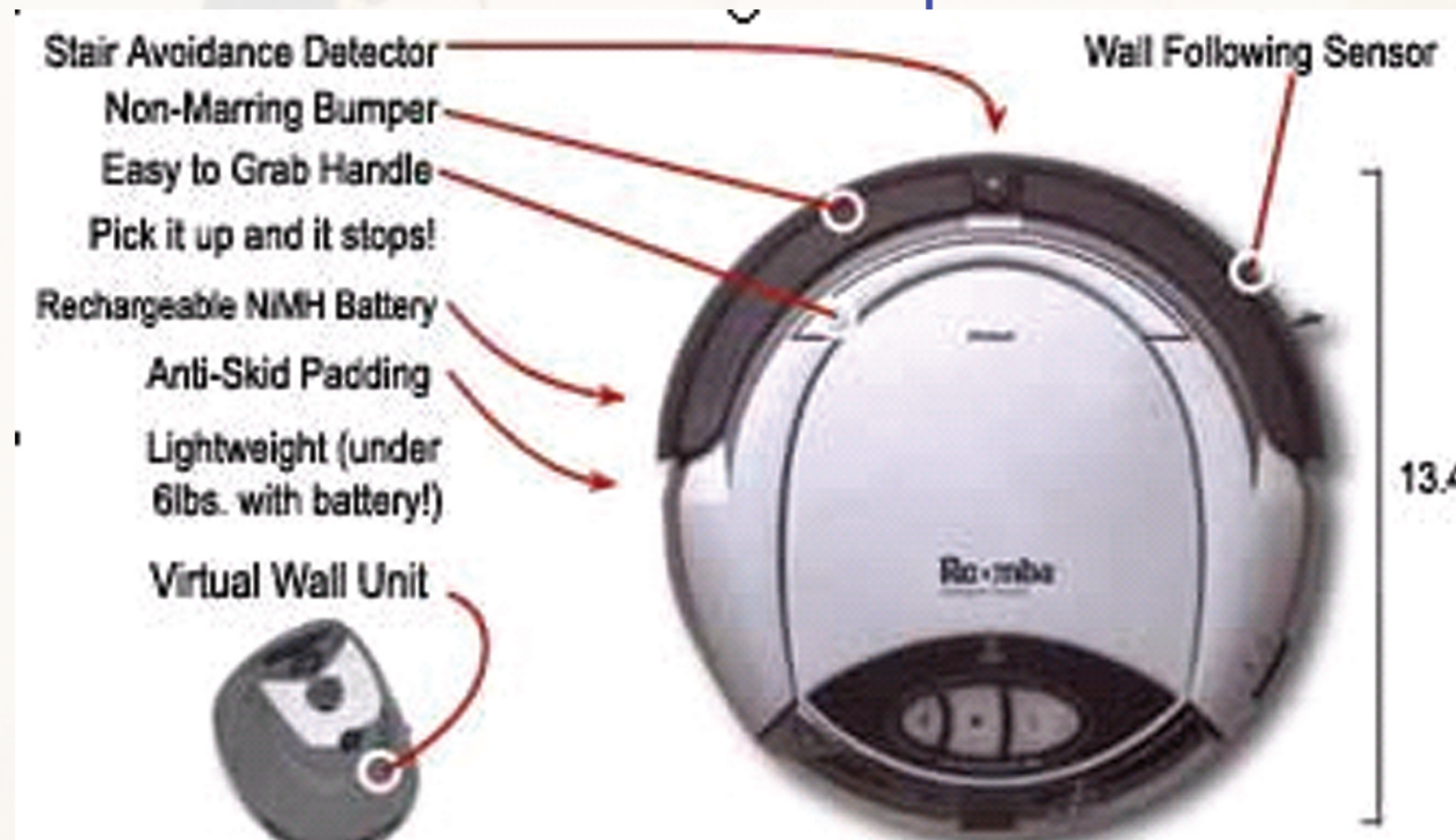
*FUTURE WORKS

- Working on sonar system
- Modification on chassis with slim materials

ROOMBA ROBOT

*INTRODUCTION

Roomba: Robotic floor sweeper created by iRobot Corporation. Patent covers only the Microcontroller Platform for robotic experiments.

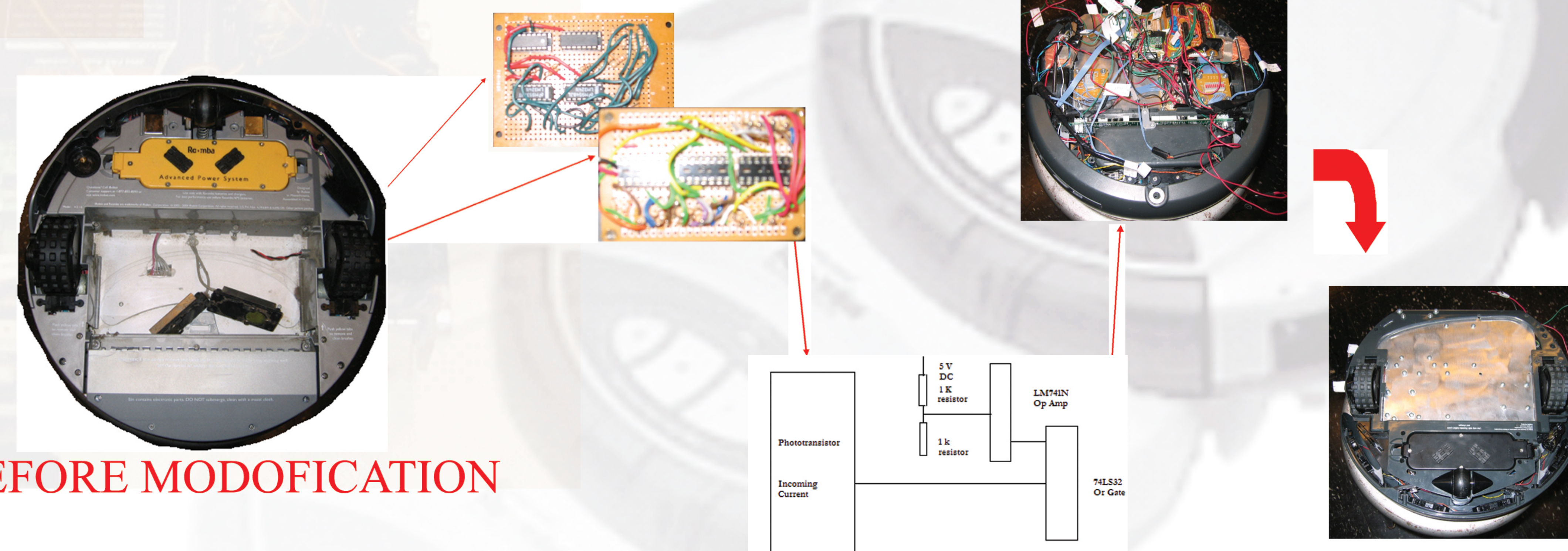


*OBJECTIVES

- Extract a prototype based on original roomba
- Creat a modified & new form of Swarm Robot
- A wonderful documentation of this prototype for the next general users.

*METHODOLOGY

- Reverse Engineering works on original Roomba
- Provide prototype based on original roomba
- Modify each component
- Creat a new form of Robot based on Roomba functions



*CONCLUSION

- Successful creation for the prototype
- Successful analysis on electrical circuit
- Provide a new form of modified Roomba
- Create a documentation of our prototype

*FUTURE WORKS

- Application on this Roomba prototype
- Neural networks between roomba robots



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